Complex RG flows for 2D nonlinear O(N) sigma models

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Motivated by recent attempts to find nontrivial infrared fixed points in 4-dimensional lattice gauge theories, we discuss the extension of the renormalization group (RG) transformations to complex coupling spaces for O(N) models on $L \times L$ lattices, in the large-N limit. We explain the Riemann sheet structure and singular points of the finite L mappings between the mass gap and the 't Hooft coupling. We argue that the Fisher's zeros appear on "strings" ending approximately near these singular points. We show that for the spherical model at finite N and L, the density of states is stripwise polynomial in the complex energy plane. We compare finite volume complex flows obtained from the rescaling of the ultraviolet cutoff in the gap equation and from the two-lattice matching. In both cases, the flows are channelled through the singular points and end at the strong coupling fixed points, however strong scheme dependence appear when the Compton wavelength of the mass gap is larger than the linear size of the system. We argue that the Fisher's zeros control the global properties of the complex flows. We briefly discuss the implications for perturbation theory, proofs of confinement and searches for nontrivial infrared fixed points in models beyond the standard model.

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I. INTRODUCTION

Recently, there has been a renewed interest [1–9] in the possibility [10] of finding nontrivial infrared (IR) fixed points in asymptotically free gauge theories with enough matter fields. A particularly interesting situation is when in addition of the nontrivial IR fixed point one ultraviolet (UV) fixed points also appears at larger coupling. It has been argued [11, 12] that in this type situation, a parameter can sometimes be varied in such a way that these two fixed points coalesce and then disappear in the complex plane.

This observation has motivated us [13] to study complex extensions of renormalization group (RG) flows in the complex coupling plane. The main result is that the Fisher's zeros - the zeros of the partition function in the complex coupling plane - act as a "gate" for the RG flows ending at the strongly coupled fixed point. This can be seen as a complex extension of the general picture proposed by Tomboulis [14] to prove confinement: the gate stays open as the volume increases and RG flows starting in a complex neighborhood the UV fixed point (where we have asymptotic freedom) may reach the IR fixed point where confinement and the existence of a mass gap are clearly present.

More generally, constructing RG flows in complex spaces could improve our understanding of the convergence of expansions (such as weak coupling and strong coupling expansions) that are used in the neighborhood of fixed points. Even though, complexification is often used for hydrodynamical flows, we are only aware of two previous studies of complex RG flows: one for exactly solvable lattice models [15] and one discussing the possibility of chaotic behavior in the decimation of one-dimensional Ising models with complex coupling [16].

In the following we discuss two complex extensions of RG flows for O(N) models on $L \times L$ lattices, in the large-N limit. The models are introduced in Sec. II. We provide a closed form expression for the partition function in the approximation where the non-zero modes of the Lagrange multiplier are neglected. This is justified in the large-N limit where we have equivalence with the spherical model. In Sec. III, we study the map between the mass gap M^2 and the 't Hooft coupling $\lambda^t = 1/b$. We show that the map requires a Riemann surface with q+1sheets and 2q cuts in the λ^t plane, where q is an integer of order L^2 . By connecting the sheets in a specific way, we construct one circle at infinity in the λ^t plane (or around 0 in the b plane) that maps into the circle at infinity in the M^2 plane and q others that maps in small regions near real interval [-8,0].

In Sec. IV, we use the closed form of the partition function of Sec. II to calculate the Fisher's zero at finite L and N. We show empirically that these zeros appear on "strings" coming from infinity in the b plane and ending near the singular points of the map discussed in Sec. III. This is consistent with the infinite volume picture provided in Ref. [17]. The density of zeros on these strings scales like L^2 and N. The results of this section can be compared to what is found for other models, for instance in Refs. [18–21] where one and two-dimensional structures have been observed.

In Sec. V, we show that the density of states is piecewise polynomial on q horizontal strips in the energy plane. We discuss the conjecture that connects the Fisher's zeros with the zeros of the second derivative of the logarithm of the density of states. In Sec. VI, we extend two RG methods to the complex b plane. The first one is based on a simple rescaling of the cutoff in the gap equation. The second one is a procedure called the two-lattice matching [22, 23]. All the numerical calculations

are done with L and N even.

Before embarking into the technical discussion, it is important to keep in mind our various motivations. From a practical point of view, it is easier to calculate Fisher's zeros than to construct RG flows and establishing a clear connection should provide more robust ways to decide about the existence of nontrivial IR fixed points. The more general question of understanding the analytic properties of the map between the coupling and the mass gap in the complex plane is also important and includes the correction to asymptotic scaling. This question can be studied explicitly for the models considered here and the results illustrate the intricate pattern that can be produced by combining lattice artifacts and finite size effects. Possible implications for lattice gauge theory will be discussed in the conclusions.

II. THE MODEL

The partition function for the O(N) nonlinear sigma model on a square, or more generally hypercubic lattice with volume $V = L^D$ reads:

$$Z = C \int \prod_{\mathbf{x}} d^N \phi_{\mathbf{x}} \delta(\vec{\phi}_{\mathbf{x}}.\vec{\phi}_{\mathbf{x}} - 1) e^{-(1/g_0^2) \sum_{\mathbf{x}, \mathbf{e}} (1 - \vec{\phi}_{\mathbf{x}}.\vec{\phi}_{\mathbf{x}+e})} ,$$

We denote the inverse 't Hooft coupling as $b \equiv 1/\lambda^t \equiv 1/g_0^2 N$. The constraint $\vec{\phi}_{\mathbf{x}}.\vec{\phi}_{\mathbf{x}} = 1$ can be implemented by introducing a Lagrange multiplier $M_{\mathbf{x}}^2$ at every lattice site. After this is done, the action becomes quadratic in $\vec{\phi}$ and the Gaussian integration can be performed. It can be shown that in the large-N limit only the zero mode of the Lagrange multiplier, denoted M^2 hereafter, survives [24]. With this simplification, the partition function becomes:

$$Z(b) = \frac{\Gamma(\frac{NV}{2})}{2\pi i (\frac{bNV}{2})^{\frac{NV}{2} - 1}} \oint_C dM^2 e^{\frac{VN}{2} [bM^2 - \mathfrak{L}(M^2)]}$$
(2)

with

$$\mathfrak{L}(M^2) = \frac{1}{V} \sum_{\mathbf{k}} \ln[2 \sum_{i=1}^{D} (1 - \cos(k_i)) + M^2].$$
 (3)

The contour of integration, denoted C, encircles the real interval [-8,0], also called "the cut". When Reb>0, C can be deformed into a vertical line with an arbitrary positive real part and a semi-circle at infinity going counterclockwise from $\pi/2$ to $3\pi/2$ which gives no contribution in the limit of infinite radius. Similarly, when Reb<0, C can be deformed into a vertical line with a negative real part smaller than -8 and a semi-circle at infinity going clockwise from $\pi/2$ to $-\pi/2$. The prefactor has been adjusted in order to have Z(0)=1 and the finite volume momenta take the values $\mathbf{k}=\frac{2\pi}{L}\mathbf{n}$ with \mathbf{n} a vector of integers modulo L.

For N even, the exponential of $-V(N/2)\mathfrak{L}(M^2)$ is a product of poles located at the real negative values

$$M_j^2 = -2\sum_{i=1}^D (1 - \cos(k_i))$$
 (4)

The integer j indexes the various values taken while \mathbf{k} runs over its V possible values $\mathbf{k} = \frac{2\pi}{L}\mathbf{n}$. The number of distinct poles will be discussed in section III where it is denoted q+1. The number of times a given value of M_j^2 occurs will be denoted n_j and we have $\sum_j n_j = V$.

By calculating the residues, we get a general expression of the form

$$Z(b) = \sum_{i,j} a_{ij} (\frac{1}{b})^i e^{\frac{V N b M_j^2}{2}} , \qquad (5)$$

where a_{ij} are coefficients depending on the order i and the pole M_j^2 . For a given j, the pole is of order $n_j N/2$ and the index i runs between VN/2-1 and $(V-n_j)N/2$. An explicit expression for D=2, L=4, N=2 is given in Eq. (A.1) in the Appendix. Despite the apparent singularities at b=0, Z(b) is an entire analytical function and has a regular expansion at b=0. For instance for D=2, L=4, N=2

$$Z(b) = 1 - 64b + \frac{35328b^2}{17} - \frac{2326528b^3}{51} + O(b^4)$$
 (6)

If in addition L is even, then for every M_j^2 , there is an associated $M_{j'}^2 = -8 - M_j^2$ obtained by changing all the k_i into $\pi - k_i$ and one can see that $a_{ij'} = (-1)^i a_{ij}$. This guarantees that

$$Z(-b) = e^{b4VN}Z(b) \tag{7}$$

as explained in [17].

It should be noted that the number of independent a_{ij} grows like $L^2 \times N$. This proliferation of terms makes calculations performed in the next sections slow when L or N becomes too large. For illustrative purpose, we will often use L=4 and N=2. This allows us to give explicit formulas of decent size as in the Appendix. However, it should be kept in mind that Eq. (2) is only a good approximation of the original partition function (Eq. (1)) for large N.

III. THE GAP EQUATION, SINGULAR POINTS, AND CUTS

In the large-N limit, it is possible to calculate the partition function in the saddle point approximation. Varying M^2 , we obtain the gap equation:

$$b = d\mathfrak{L}(M^2)/dM^2 \equiv \mathfrak{B}(M^2) , \qquad (8)$$

with

$$\mathfrak{B}(M^2) \equiv (1/V) \sum_{\mathbf{k}} \frac{1}{2(\sum_{i=1}^{D} (1 - \cos(k_i)) + M^2)}$$
(9)
= $(1/V) \sum_{j=1}^{q+1} \frac{n_j}{M^2 - M_j^2}$ (10)

where n_j is the number of times the pole M_j appears in the sum over the \mathbf{k} and q+1 the number of distinct poles. The explicit form of $\mathfrak{B}(M^2)$ in the case D=2 and L=4 is given in Eq. (A.2) in the appendix. From now on D=2 is assumed in all the examples. The precise value of q depends on accidental degeneracies but generally increases like L^2 . From Fig. 1 and Table II, we see that most of the values of 2q follow the relation $(L/2+1)^2$ or $(L/2+1)^2-1$ with exceptions every three or six data points. In general, after reducing to a common denominator, we obtain a rational form:

$$\mathfrak{B}(M^2) = Q(M^2)/P(M^2) , \qquad (11)$$

where Q and P are polynomials of degrees q and q+1 respectively.

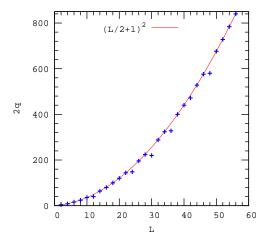
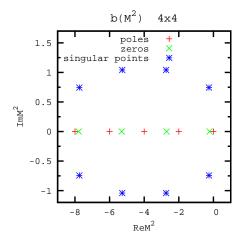


FIG. 1. Relation between L and 2q for D=2.

We now discuss the poles, zeros and singular points of the mapping between b and M^2 given by the gap equation (8). From Eq. (4), the q+1 poles of \mathfrak{B} are real and between -8 and 0. -8 and 0 are always poles and on the real interval between them (that we call "the cut" hereafter), $\mathfrak{B}(M^2)$ is zero once between each pair of successive poles. In addition of these q zeros, $\mathfrak{B}(M^2)$ is also zero when M^2 becomes infinite. This also makes q+1 zeros. In general, $b=\mathfrak{B}(M^2)$ takes all the complex values q+1 times when M^2 is varied over the whole complex plane. Thus, the inverse map between the mass gap M^2 and b requires a Riemann surface with q+1 sheets in the b plane. To decide where to put the cuts and how to join different sheets, we need to study the singular points



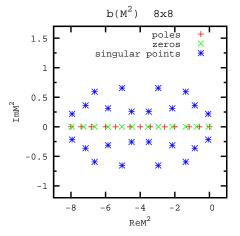


FIG. 2. Zeros, poles and singular points of $b(M^2)$ in the M^2 plane for 4×4 and 8×8 lattices.

where $\partial b/\partial M^2=0$. This occurs when P'Q-PQ', a polynomial of degree 2q, vanishes. The 2q roots of P'Q-PQ' appear in complex conjugate pairs in M^2 plane. This is illustrated in Fig. 2 for L=4 and 8. We notice that as L increases the region where the singular points appear shrinks along the cut. A log-log plot of the largest imaginary part of the singular points versus L is rather irregular but suggests that the height of the region where the singular points appear is of the order 1/L. In the infinite volume limit, the singular points become dense and cover the [-8,0] cut.

The image of a singular point M_{sing}^2 in the b plane is $\mathfrak{B}(M_{sing}^2)$. At infinite volume, $\mathfrak{B}(M^2)$ becomes an integral with four logarithmic singularities [17]. The image of two lines of points located very close above and below the [-8,0] cut, span four curves forming a cross shaped figure that can be seen in Fig. 3. For comparison, the 288 singular points for a 32×32 lattice are also displayed. We find that the real part of the closest singular points (CSP) move to infinity while the imaginary part stay at $\frac{1}{8}$ as the volume increases. Near a singular point M_{sing}^2 , we have $(\mathfrak{B}(M_{sing}^2 + \delta z) - \mathfrak{B}(M_{sing}^2)) \propto (\delta z)^2$ and we need

two sheets to invert the function in the neighborhood of $\mathfrak{B}(M^2_{sing.})$.

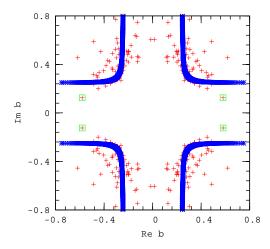


FIG. 3. The blending small crosses (x, blue online) are the b images of two lines of points located very close above and below the [-8,0] cut in infinite volume; the crosses (+) are the images of the singular points for L=32. The images of the 4 closest singular points appear as boxes.

In order to construct the q + 1 sheets, we start with the region of the M^2 plane where $|M^2+4| >> 8$. In this region we have $b \simeq 1/M^2$. We call this sheet the "main" sheet because it contains the usual strong coupling region where b is small, real and positive corresponding to a m_{gap}^2 large, real and positive. As we now consider smaller values of $|M^2+4|$, and correspondingly larger values of b on the main sheet, we start running into singular points and need to decide on the location of the cuts. A simple choice is to take the cuts on vertical lines in the bplane going from the images of singular points with positive imaginary part to increasing values of the imaginary part and from the images of singular points with negative imaginary part to decreasing values of the imaginary part. The cuts are shown for L=4 in Fig. 4. We can now construct the inverse image of the two branches of a cut on the main sheet. They end up on two real negative values of M^2 where b becomes infinite. The complex conjugate of the inverse image of these two branches corresponds to the complex conjugated cut in the b plane. Joining the two together, we obtain an oval shaped region in the M^2 plane located symmetrically across the cut. If we vary M^2 inside each of the oval shapes, b runs over the whole complex plane forming the other q sheets. This construction is illustrated for L=4 where q=4 in Fig. 4. If a curve in the M^2 plane enters an oval shaped region say on the left of the critical point and exits on the right of this critical point, then its image in the b plane will wrap around the image of the singular point. In Section VI, we will show that the cuts in the b plane and the boundaries of the oval shaped regions are important to understand the RG flows.

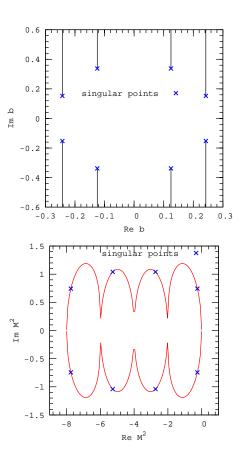


FIG. 4. Singular points and cuts in the b plane for L=4 (top) and their inverse images in the M^2 plane.

IV. FISHER'S ZEROS

In this section, we discuss the Fisher's zeros of the partition function at finite N and L and the way their density scales with these quantities. Later we will show that these zeros play an important role in controlling the RG flows. The coefficients a_{ij} in the large-N expression Eq. (5) can be calculated exactly at finite N and L using the residues theorem. We can then search for the zeros of the partition function by using Newton's method and check that the number of zeros found inside a given region of the b plane encircled by a closed curve C is consistent with

$$\oint_C db(dZ/db)/Z = i2\pi \sum_q qn_q(C) , \qquad (12)$$

where $n_q(C)$ is the number of zeros of order q inside C. The results are shown in Fig. 5 for L=6. We see that the zeros form linear structures ("strings") ending at locations close to the (N-independent) singular points. Similar pictures are found for other not too large values of L and N where similar calculations are feasible. In all the examples considered, we also found that the zeros closest to the real axis always have an imaginary part

larger than 1/8 in absolute value, in other word they never get closer to the real axis than the CSP.

The density of zeros increases with N and L. We calculated the density of zeros in the b plane (number of zeros in a given area of the b plane taken as large as possible). The results are shown in Fig. 6. The fits of these log-log plots show that at fixed L=2, the density grows like $N^{1.000}$ and at fixed N=2, the density grows like $L^{2.027}$. This data is consistent with the idea that the density of zeros increases like the number of fields (NV).

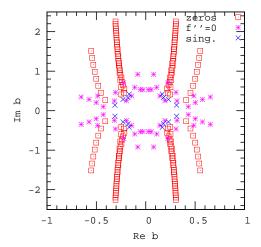


FIG. 5. Zeros of partition function for L=6, N=2 (boxes), and images of the singular points of $b(M^2)$ (crosses). The images of the solutions f''=0 discussed in section V are given with the third symbol

V. DENSITY OF STATE

Another way to obtain information about the location of the Fisher's zeros is to calculate the density of states n(E) in the complex energy plane. First, we consider the case where the energy E is real. The density of states n(E) is the inverse Laplace transform of the partition function:

$$n(E) = \frac{N}{2\pi i} \int_{K-i\infty}^{K+i\infty} db e^{bNE} Z(b) . \qquad (13)$$

The contour of integration is a vertical line in the complex b plane with a constant positive real part K otherwise arbitrary. For L even, the relation between Z(b) and Z(-b) given in Eq. (7) implies that

$$n(4V - E) = n(E) . (14)$$

We can now use the form of the partition function given in Eq. (5) to obtain an explicit form. The only poles of the integrand are at b=0. If $E+\frac{V}{2}M_j^2>0$, we can close

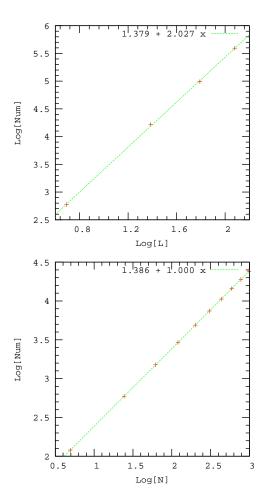


FIG. 6. Number of zeros in a fixed region of the b-plane for $N=2,\ L$ variable (top) and $L=2,\ N$ variable (bottom)

the contour by adding a semi-circle at infinity to the left and calculate the residue of the pole of order i at b=0. If $E+\frac{V}{2}M_j^2<0$ we can close the contour by adding a semi-circle at infinity to the right and the closed contour includes no poles. Since all the M_j^2 are real and negative, it is clear that n(E)=0 for E<0. For L even, Eq. (14) implies that that n(E)=0 for E>4V. The final result for E real and E and E0 even is that the density of states is piecewise polynomial for E1 even will be given in Eq. (15).

We now generalize this construction to the case where E is complex. If we consider e^{bNE} on a circle at infinity in the b plane, the expression blows up on one-half of the circle and decays on the other half. If we insist on being able to define the density of states by integrating Eq. (5) term by term then the only way to extend the definition is to rotate the line integral in such a way that bE is purely imaginary at both ends. The argument about the closing of the contour goes as before and we enclose the

poles at 0 if $Re(E + \frac{V}{2}M_i^2) > 0$. The final result is:

$$n(E) = N \sum_{i,j} a_{ij} \frac{(NE + \frac{NV}{2}M_j^2)^{i-1}}{(i-1)!} \theta(Re(E + \frac{V}{2}M_j^2)) .$$
(15)

Fig. 7 shows the function for L=4 and N=2 following an explicit formula given in Eq. (A.3) in the appendix.

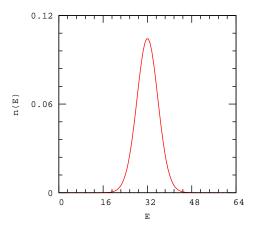


FIG. 7. Density of state function for L=4 and N=2

In summary, we have constructed a complex extension of the density of states that is stripwise polynomial in the complex E plane. As the polynomials associated with n(E) in two contiguous strips are different, it is unavoidable that some of their derivatives will be different at the boundary. However the discrepancies only appear at some order that increases with VN/2. This can be seen from the discussion in Section II, where we discuss the range of powers of 1/bappearing in the partition function. As we cross the boundary of a strip $Re(E) = V|M_i^2|/2$, we add terms of the form $(E + \frac{\hat{V}}{2}M_j^2)^{i-1}$ which vanish at the boundary if i > 1. This term generates a discontinuity in the i-1-th derivative. The lowest value of i occurring is $(V - n_j)N/2$, where n_j is the number of times the pole M_i^2 appears. Consequently, the lowest derivative at which a discontinuity occurs is $(V - Max_i(n_i))N/2 - 1$. For instance, for L = 4, $Max_i(n_i) = 6$, and the lowest order is 5N-1. It can indeed be proven that for L even, $Max_j(n_j) = 2(L-1)$ and that it corresponds to $M_i^2 = -4$ for which "mirror" momenta can be paired in måximal number.

Interestingly, we can use the large-N limit to obtain finite volume thermodynamics from the density of states. At large N, by saddle point approximation of the Laplace transform of Eq. (13), we obtain that

$$b(E) \equiv f' = \frac{n'(E)}{Nn(E)} , \qquad (16)$$

which is similar to the standard thermodynamical relation $\beta = \partial S/\partial E$.

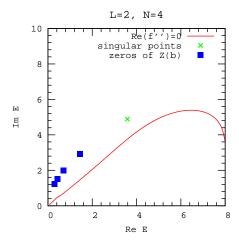


FIG. 8. Singular points, zeros of partition function, and Re(f'')=0 in E plane for L=2, N=4. The line (red online), corresponds to Re(f'')=0 with Re(f'')>0 above it.

Eq. (16) provides a mapping of vertical strips of the E plane into the b-plane. The solutions of f''(E) = 0 give the singular points of this mapping. These singular points can be found strip by strip by finding the solutions of the polynomial equation:

$$n(E)n''(E) = (n'(E))^2$$
, (17)

that belongs to that vertical strip (assuming that $n(E) \neq 0$). We can then compare the *b*-images of these singular points using Eq. (16) strip by strip. Fig. 5 shows the images of these singular points for L=6, N=2 together with the images of the singular points of $b(M^2)$ and the zeros of partition function in *b* plane. We see that the singular points of b(E) seem to cluster is the same region as the singular points of $b(M^2)$ but with a slightly broader range. We conjecture that in the infinite volume limit, both types of singular points will accumulate on the outside boundary of the crossed shaped curve displayed in Fig. 3 (image of the cut in the infinite volume limit).

In the saddle point approximation, it can be argued [25], that Fisher's zeros can only appear as images of regions in the E plane where Re(f'') > 0. In Fig. 8, we see that the inverse image of the Fisher's zeros appears in the region Re(f'') > 0 even at small values of N and L.

VI. COMPLEX RG FLOWS FOR O(N)

In this section, we construct complex RG flows using two different methods. The first one is based on a rescaling of the UV cutoff in $b(M^2)$ given by the saddle point relation Eq. (8), the second is a complex extension of the two-lattice matching proposed in Ref. [22, 23]

A. Rescaling of M^2

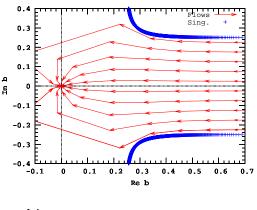
Eq. (8) can be interpreted as a relation between the bare coupling and the UV cutoff keeping the renormalized mass, or mass gap, fixed. As the UV cutoff is lowered, the coupling increases and ultimately, b flows to zero. More specifically, $M^2 = m_R^2/\Lambda^2$ and we follow the change in bunder the change $\Lambda \to \Lambda/s$. In the literature the rescaling factor s is often denoted b, but we are already using this symbol for the inverse 't Hooft coupling. Under this change, $M^2 \to s^2 M^2$ and we can follow the trajectory in the b plane. In the following, we will iterate the transformation with s=2 in order to allow a comparison with the other method for which s=2 is the simplest possibility. The initial values of M^2 were taken on a small circle around the origin in the M^2 plane and then multiplied repeatedly by 4. We can visualize these trajectories as "rays" coming out of the origin in the M^2 plane.

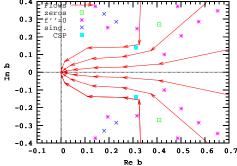
At infinite volume, as long as the trajectories in the M^2 do not cross the cut, the corresponding trajectories in the b plane will stay inside the cross shaped image of the cut shown in Fig. 3. Sample trajectories are shown on Fig. 9 a) and illustrate this idea. The flatness of the flow at larger values of Reb can be understood from the approximate logarithmic scaling of b and the fact the rescaling factor is real and does not affect the phase of the rays.

At finite volume, the cut acquires a thickness and a structure described in Sec. III. If the ray crosses the oval shaped regions on two sides of the singular point (see Fig. 4), then the corresponding trajectory in the b plane will wrap around the image of the singular point in the b plane using another Riemann sheet. At very small M^2 , we have $b(M^2) \simeq 1/(L^2M^2)$ (instead of a logarithmic dependence) and we have inverted rays at infinity in the b plane. By small, we mean that the other poles at M_j^2 can be neglected which occurs if $M^2 << 1/L^2$, in other words, if the Compton wavelength is larger than the volume of the system. Sample trajectories are shown in Fig. 9 b) for L=6. The two singular points which have the closest distance to the real axis are called the closest singular points (CSPs).

B. Two-lattice matching

The 2-lattice matching [22, 23] is another method that can be used to obtain complex RG flows. We will be matching observables R(b,L) from systems with different lattice spacing but equal physical sizes. Under a RG transformation, the lattice spacing increases $(a \to sa)$ and the number of sites decreases $(L \to L/s)$, but the physical length La stays constant. In the following, we compare a $2^n \times 2^n$ lattice with 't Hooft coupling b with a $2^{n-1} \times 2^{n-1}$ lattice with 't Hooft coupling b'. The $2^n \times 2^n$ model is blocked n-1 times while the coarser lattice model is blocked n-2 times. For an arbitrary lattice with $L=2^q$, we define the ratio of correlations of





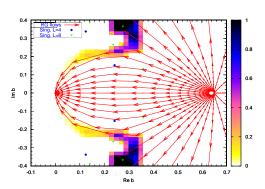


FIG. 9. a) (up) RG flows by rescaling and image of the cut at infinite volume; b) (bottom) flows by rescaling, singular points, CSPs, zeros of partition functions (N=2), and f''=0 (N=2) in b plane for 6×6 lattice system. c) RG flows for the 2-lattice matching between 8×8 and 4×4 lattices. Circles and triangles are the singular points for L=4 and L=8.

block observables (sum of all the spins inside a $L/2 \times L/2$ block B or its nearest neighbor block NB).

$$R(b,L) \equiv \frac{\left\langle (\sum_{x \in B} \vec{\phi}_x) (\sum_{y \in NB} \vec{\phi}_y) \right\rangle_{b,L}}{\left\langle (\sum_{x \in B} \vec{\phi}_x) (\sum_{y \in B} \vec{\phi}_y)) \right\rangle_{b,L}} . \tag{18}$$

Note that R(b, L) is independent of the rescaling of the fields that needs to be performed in order to get an explicit form for the RG transformation. Note also that in order to define the numerator and denominator separately, we need to divide by the partition function, but

these normalization factors cancel in the ratio. In the large-N limit, the correlations are the same as for a Gaussian model with a mass M^2 defined as a function of b by Eq. (8). By using the binary decomposition of the integers between 1 and 2^{n-1} , in the Fourier decomposition of the two-point function, we obtain

$$\left\langle \left(\sum_{x \in B} \vec{\phi}_x\right) \left(\sum_{y \in NB} \vec{\phi}_y\right) \right\rangle_{b,2^n} = \sum_{\mathbf{k}} \cos(2^{n-1}k_1) \mathfrak{H}(\mathbf{k}) \mathfrak{G}(\mathbf{k}) ,$$

$$\left\langle \left(\sum_{x \in B} \vec{\phi}_x\right) \left(\sum_{y \in B} \vec{\phi}_y\right) \right\rangle_{b,2^n} = \sum_{\mathbf{k}} \mathfrak{H}(\mathbf{k}) \mathfrak{G}(\mathbf{k}) , \qquad (19)$$

with

$$\mathfrak{H}(\mathbf{k}) = \prod_{l=1}^{n-1} [(1 + \cos(2^l k_1))(1 + \cos(2^l k_2)) , \qquad (20)$$

and the lattice propagator

$$\mathfrak{G}(\mathbf{k}) = 1/[2(2 - \cos(k_1) - \cos(k_2)) + M^2] . \tag{21}$$

After performing the sums over the momenta, $R(b, 2^n)$ reduces to a ratio of polynomials in M^2 understood as function of b. Examples are given in Eqs. (A.4-7) in the appendix. As explained in Sec. III, there are q+1 values of M^2 corresponding to one values of b. In the following, we always select the value corresponding to the "main sheet". This includes the circle at infinity where the conventional strong coupling behavior applies. In other words, we exclude the q other values of M^2 corresponding to the small oval shaped region surrounding the cut.

A complex RG map can be constructed as follows. Given an initial complex value of b, we determine $M^2(b)$ corresponding to the main sheet. Using Eqs. (18-19), this result in a unique numerical value for $R(b, 2^n)$. We then match this number with $R(b', 2^{n-1})$ expressed as a ratio of polynomials in M'^2 . This results in a certain number of solutions for M'^2 . We only keep the ones corresponding to the main sheet. Each of these selected solutions determines a unique value of b'. If more than one remain, we only keep the one closest to b. In order to quantify the level of ambiguity associated with this choice, we define the ambiguity A as

$$A = \frac{|b - b'|_{min}}{|b - b'|_{next - to - min}} , \qquad (22)$$

where $|b-b'|_{min}$ is the distance between b and the closest solutions and $|b-b'|_{next-to-min}$ the distance to the next closest solution. If there is only one solution A=0 ($|b-b'|_{next-to-min}=\infty$). There is also the logical possibility that none of the M'^2 solutions correspond to the main sheet, but we never encountered this case in practical calculations. In Fig. 9c), light regions correspond to small values of A while dark-colored regions stand for values of A close to 1 (maximal ambiguity). When

 $|b-b'|_{min} \simeq |b-b'|_{next-to-min}$ it is not clear that we can define a RG flow, and not surprisingly chaotic behavior is often observed in these circumstances. Unambiguous flows tend to stay in light-colored regions while ambiguous flows go into the dark regions and jump to other fixed points. By looking at all the singular points, we find that the closest singular points (CSP) are close to the edges of dark-colored regions, which gives us the idea that the unambiguous RG flows are bounded by the singular points and the features of all the RG flows are controlled by the CSP. Fig. 9 shows the RG flows starting from the first fixed point on the real positive axis($b_0 = 0.64$) with the singular points of 4×4 and 8×8 lattice systems.

In order to understand the fixed points on the real axis more systematically, we study the RG transformation in the small M^2 , large b limit. For very small M^2 , the pole at zero dominates in Eq. (8) and we have $b \simeq 1/(M^2L^2)$. The other poles have small contributions provided that $M^2 << 1/L^2$, in other words, when the Compton wavelength is larger than the linear size of the system. In the same limit, the matching condition becomes

$${M'}^2 \simeq 4(1 - A/L^2)M^2$$
, (23)

with A a constant that we will determine later. We now only consider the real solutions of b and calculate the change of the coupling $\Delta b \equiv b-b'$. Numerical results are shown in Fig. 10 where a comparison with the rescaling method is made. In the infinite volume limit, the rescaling from M^2 to $4M^2$ leads to the relation: $\Delta b = \frac{1}{2\pi} \ln 2$ and for large b, there is no nontrivial fixed point. Putting everything together, we get the approximate finite volume formula:

$$\Delta b(b) \simeq -(A/L^2)b + \frac{\ln 2}{2\pi}$$
 (24)

This implies the that we have an approximate fixed point

$$b_{app.}^{\star} \equiv \frac{\ln 2}{42\pi} L^2 \tag{25}$$

In Table.I, we compare the numerical fixed points $b_{num.}^{\star}$ with the approximate $b_{app.}^{\star}$ with A=30.5, and find the approximate model provides reasonable estimates for large volume. For comparison, Δb can also be calculated with the rescaling method. In this case $M'^2=4M^2$ and if M^2 is finite and nonzero, the denominator of all the terms is b' are strictly larger than for b, consequently b' < b and there is no nontrivial fixed point. In summary, we see that discrepancies between the two RG methods occur in the limit where the Compton wavelength is larger than the size of the system. Otherwise, the RG flows going through the CSP are very similar for the two methods.

C. Comparison of the two methods

In this subsection we argue that in the infinite volume limit, the two RG flows discussed in the two previous

L	$b_{num.}^{\star}$	$b_{app.}^{\star}$
4	0.320	0.058
8	0.648	0.23
16	1.47	0.93
32	4.36	3.70
64	15.5	14.82
128	59.9	59.3
256	237	237

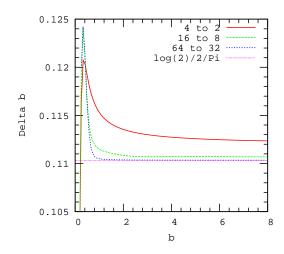
TABLE I. Numerical solutions of fixed points and approximate solutions from $\Delta b=0$

subsections should coincide. By construction, the infinite volume of the RG flows illustrated in Fig. 9 b) turn into those of Fig. 9 a). It is nevertheless interesting to figure out in detail how it occurs. As we take initial conditions corresponding to $M^2 = \epsilon e^{i\theta}$, we see that as θ becomes slightly larger than $\pi/2$, the linear RG trajectories in the M^2 plane cross the rightest oval shaped region discussed in Sec. III on the both sides of the upper singular point. As a consequence, the corresponding RG flows in the b-plane wrap around the CSP which is the image of the first singular point, before going to 0. In the infinite volume limit, the CSP moves to infinity and we recover Fig. 9 a). In some sense, the finite volume provides a regularization and gives a mathematical meaning to what happens for initial conditions corresponding to the cut.

The two-lattice matching relies on the fact that if we apply the RG transformation enough times, the RG flows are projected on the unstable manifold which is one-dimensional for the models considered here. In this limit, the flows from the two lattices can be compared unambiguously. From the way we set up the calculation, it is clear that we reach an infinite number of RG transformation in the infinite volume limit (we block-spin $\ln_2(L)$ times). In this limit, the finite volume fixed point goes to infinity like L^2 and it is plausible that the unambiguous flows of Fig. 9 c) become similar to those of Fig. 9 a).

VII. CONCLUSIONS

In summary, we have extended two types of RG transformations to complex coupling spaces for O(N) models on $L \times L$ lattices in the large-N limit. The three graphs of Fig. 9 illustrate possible outcomes in models where calculations are more difficult such as asymptotically free lattice gauge theories. Our general expectation is that at infinite volume, almost horizontal flows come from the large β region where the logarithmic scaling characteristic of asymptotic freedom holds. The flows are then funneled through a continuous boundary whose shape is a lattice artifact. For instance, if we had used a continuum model with a sharp cutoff, the boundary would be flat instead of the shape seen in Fig. 9 a). The existence of this boundary reflects the fact that we try to extend



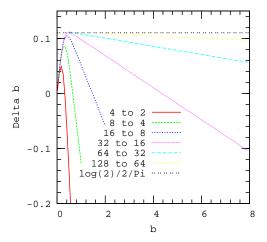


FIG. 10. Δb versus b from rescaling (top) and 2-lattice matching (bottom).

the mapping between M^2 and b, we encounter a cut in the M^2 plane and the boundary is the image in the b plane of a close curve tightly enclosing the cut.

At finite volume, the continuous boundary is replaced by a loosely defined region where complicated or ambiguous trajectories are observed (see also Fig. 1 in Ref. [13]). Empirically, this region seems to coincide with the region where the images of the singular points of the mappings $b(M^2)$ or b(E), and the ends of strings of Fisher's zeros appear. As the volume increases, the number of zeros in a fixed area of the b-plane increases like the volume and N and we believe that the Fisher's zeros become dense outside of the boundary mentioned above. Fig. 3 in Ref. [13] suggests that it will also be the case in lattice gauge theory. Our numerical study supports the idea that by monitoring the lowest zeros of asymptotically free theories when the volume increases, we can determine if the RG flows reach the region where a mass gap is present or if instead a nontrivial IR fixed point is encountered.

We are planning to investigate the scaling of the Fisher's zeros in SU(3) N_f flavors and also to investigate the question of the corrections to asymptotic scaling [26] in the complex plane.

The complex flows described here are in some sense the simplest possible ones and we expect similar complex flows for SU(2) lattice gauge theory in 4 dimensions. In contrast, for U(1) lattice gauge theory in 4 dimensions it appears that the Fisher's zeros pinch the real axis as L^{-x} [27] with $2 \le x \le 4$. A more precise estimate for x will be discussed in a forthcoming preprint [28]. In this case, we expect complex RG flows similar to those of the 3 dimensional Ising or O(N) models where two phases are present.

Complex flows for models with a conventional secondorder phase transition have been constructed for the hierarchical model [13]. More recently, it has been found that the qualitative behavior of the complex flows can be modified by lowering the adjustable parameter (usually denoted c) below the critical value (c=1) where a second order phase transition is possible. As c reaches 1, the nontrivial fixed point moves to infinity. As c is further lowered, a pair of complex conjugated nontrivial complex fixed points appear [29]. In general, it seems likely that by considering actions with tunable parameters, it is possible to create interesting patterns for the complex RG flows. For hierarchical models with slightly modified interactions, it is possible to create additional fixed points and study their effects on the discrete $\Delta\beta$ function. In particular, we would like to understand if by constructing a continuous Calan-Symanzik β reproducing approximately the discrete one, it is possible to relate the nontrivial complex fixed points to the complex zeros of the continuous β function. This will also be discussed in Ref. [29].

For the models considered here, a richer complex flow behavior could be obtained by adding new terms in the energy function and considering higher dimensional complex flows. One possibility that comes to mind is to add a term inspired by the Witten-Wess-Zumino term in the continuum. Multidimensional RG flows can exhibit intricate global properties sorted in Ref. [30]. Their complexification appear to be a completely open field of investigation.

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L	2q	L	2q	L	2q	L	2q
2	4	16	80	30	220	44	528
4	8	18	100	32	288	46	576
6	16	20	120	34	324	48	580
8	24	22	144	36	328	50	676
10	36	24	148	38	400	52	728
12	40	26	196	40	440	54	784
14	64	28	224	42	472	56	840

TABLE II. L and 2q

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Appendix: Numerical examples

The numerical values of 2q for L up to 42 are given in Table II. We also provide the explicit form for the partition function, $\mathfrak{B}(M^2)$ and the density of states for D=2, L=4, N=2.

$$\begin{split} Z(b) &= -\frac{1576575e^{-128b}}{4722366482869645213696b^{15}} [3456b \left(2097152b^4 + 174080b^2 + 2655\right) e^{64b} \\ &- 5e^{128b} + 5 + 40e^{96b} \left(294912b^3 - 202752b^2 + 53472b - 5255\right) \\ &+ 40 \left(294912b^3 + 202752b^2 + 53472b + 5255\right) e^{32b}] \\ &= 1 - 64b + \frac{35328b^2}{17} - \frac{2326528b^3}{51} + \frac{737607680b^4}{969} + O\left(b^5\right) \end{split} \tag{A.1}$$

$$\mathfrak{B}_{4\times4}(M^2) = \frac{1}{16} \Big(1/M^2 + 4/(2+M^2) + 6/(4+M^2) + 4/(6+M^2) + 1/(8+M^2) \Big) . \tag{A.2}$$

$$n(E) = \frac{5}{7968993439842526298112} [-644087808(E - 48)^{11}\theta(E - 48) - 73801728(E - 48)^{12}\theta(E - 48) - 2994432(E - 48)^{13}\theta(E - 48) - 42040(E - 48)^{14}\theta(E - 48) - 10882507603968(E - 32)^{9}\theta(E - 32) - 32848478208(E - 32)^{11}\theta(E - 32) - 12845952(E - 32)^{13}\theta(E - 32) - 644087808(E - 16)^{11}\theta(E - 16) + 73801728(E - 16)^{12}\theta(E - 16) - 2994432(E - 16)^{13}\theta(E - 16) + 42040(E - 16)^{14}\theta(E - 16) + E^{14}\theta(E) - (E - 64)^{14}\theta(E - 64)].$$
(A.3)

We also give the explicit form of the first $R(b, 2^l)$ with M^2 understood as a function of b as explained in Sec. VI.

$$R(b,2) = \frac{8 + 2M^2}{8 + 8M^2 + (M^2)^2} , \qquad (A.4)$$

$$R(b,4) = \frac{2+M^2}{2+4M^2+(M^2)^2} , \qquad (A.5)$$

and

$$R(b,8) = \frac{32 + 82M^2 + 54(M^2)^2 + 13(M^2)^3 + (M^2)^4}{32 + 222M^2 + 314(M^2)^2 + 153(M^2)^3 + 30(M^2)^4 + 2(M^2)^5}.$$
 (A.6)

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